

TD1 – Intégration par parties – Proposition de correction**Calculer les intégrales suivantes (par parties)**

$$I = \int_{-3}^0 (x+1) e^{-x} dx$$

On pose $\begin{cases} u(x) = x+1 \\ v'(x) = e^{-x} \end{cases}$

on obtient : $\begin{cases} u'(x) = 1 \\ v(x) = -e^{-x} \end{cases}$

$$I = [(x+1) \cdot (-e^{-x})]_{-3}^0 - \int_{-3}^0 1 \cdot (-e^{-x}) dx$$

$$I = [(x+1) \cdot (-e^{-x})]_{-3}^0 - [e^{-x}]_{-3}^0$$

$$I = [-(x+1) \cdot e^{-x}]_{-3}^0 - [e^{-x}]_{-3}^0$$

$$I = [(-x-1) \cdot e^{-x}]_{-3}^0$$

$$I = [(-x-2) \cdot e^{-x}]_{-3}^0$$

$$I = (-0-2) \cdot e^0 - (-3-2) \cdot e^3$$

Finalement

$$I = -2 - e^3$$

$$J = \int_0^2 (-2x+4) e^x dx$$

On pose $\begin{cases} u(x) = -2x+4 \\ v'(x) = e^x \end{cases}$

on obtient : $\begin{cases} u'(x) = -2 \\ v(x) = e^x \end{cases}$

$$J = [(-2x+4) \cdot e^x]_0^2 - \int_0^2 -2 e^x dx$$

$$J = [(-2x+4) \cdot e^x]_0^2 + 2 \int_0^2 e^x dx$$

$$J = [(-2x+4) \cdot e^x]_0^2 + 2 [e^x]_0^2$$

$$J = [(-2x+6) \cdot e^x]_0^2$$

$$J = (-2 \cdot 2 + 6) \cdot e^2 - (-2 \cdot 0 + 6) \cdot e^0$$

Finalement

$$J = 2e^2 - 6$$

$$K = \int_0^1 \ln(x+3) dx$$

On pose $\begin{cases} u'(x) = 1 \\ v(x) = \ln(x+3) \end{cases}$

on obtient :

$$\begin{cases} u(x) = x \\ v'(x) = \frac{1}{x+3} \end{cases}$$

$$K = [x \ln(x+3)]_0^1 - \int_{-3}^0 \frac{x}{x+3} dx$$

$$K = [x \ln(x+3)]_0^1 - \int_{-3}^0 \frac{x+3-3}{x+3} dx$$

$$K = [x \ln(x+3)]_0^1 - \int_{-3}^0 \frac{x+3}{x+3} - \frac{3}{x+3} dx$$

$$K = [x \ln(x+3)]_0^1 - \int_{-3}^0 1 - 3 \cdot \frac{1}{x+3} dx$$

$$K = [x \ln(x+3)]_0^1 - [x - 3 \ln(x+3)]_0^1$$

$$K = [(x-3) \cdot \ln(x+3) - x]_0^1$$

$$K = (1-3) \cdot \ln(1+3) - 1 - (0-3) \cdot \ln(0+3) + 0$$

Finalement

$$K = -2 \ln 4 + 3 \ln 3$$

$$L = \int_1^e x^2 \ln x dx$$

On pose $\begin{cases} u'(x) = x^2 \\ v(x) = \ln x \end{cases}$

on obtient :

$$\begin{cases} u(x) = \frac{x^3}{3} \\ v'(x) = \frac{1}{x} \end{cases}$$

$$L = \left[\frac{x^3}{3} \ln x \right]_1^e - \int_1^e \frac{x^3}{3x} dx$$

$$L = \left[\frac{x^3}{3} \ln x \right]_1^e - \frac{1}{3} \int_{-3}^0 x^2 dx$$

$$L = \left[\frac{x^3}{3} \ln x \right]_1^e - \frac{1}{3} \left[\frac{x^3}{3} \right]_1^e$$

$$L = \left[\frac{x^3}{3} \left(\ln x - \frac{1}{3} \right) \right]_1^e$$

$$L = \frac{e^3}{3} \left(\ln e - \frac{1}{3} \right) - \left(\frac{1^3}{3} \left(\ln 1 - \frac{1}{3} \right) \right)$$

$$L = \frac{e^3}{3} \left(1 - \frac{1}{3}\right) - \left(\frac{1}{3} \left(-\frac{1}{3}\right)\right)$$

$$L = \frac{e^3}{3} \left(\frac{2}{3}\right) - \left(-\frac{1}{9}\right)$$

Finalement

$$L = \frac{2e^3 + 1}{9}$$

$$M = \int_1^3 t \ln t \, dt$$

$$\text{On pose } \begin{cases} u'(t) = t \\ v(t) = \ln t \end{cases}$$

$$\text{on obtient : } \begin{cases} u(t) = \frac{t^2}{2} \\ v'(t) = \frac{1}{t} \end{cases}$$

$$M = \left[\frac{t^2}{2} \ln t \right]_1^3 - \int_1^3 \frac{t^2}{2t} dt$$

$$M = \left[\frac{t^2}{2} \ln t \right]_1^3 - \int_1^3 \frac{t}{2} dt$$

$$M = \left[\frac{t^2}{2} \ln t \right]_1^3 - \frac{1}{2} \left[\frac{t^2}{2} \right]_1^3$$

$$M = \left[\frac{t^2}{2} \left(\ln t - \frac{1}{2} \right) \right]_1^3$$

$$M = \frac{9}{2} \left(\ln 3 - \frac{1}{2} \right) - \frac{1}{2} \left(\ln 1 - \frac{1}{2} \right)$$

$$M = \frac{9}{2} \ln 3 - \frac{9}{4} + \frac{1}{4}$$

Finalement

$$M = \frac{9}{2} \ln 3 - 2$$

$$N = \int_0^{\frac{\pi}{2}} t \cos t \, dt$$

$$\text{On pose } \begin{cases} u(t) = t \\ v'(t) = \cos t \end{cases}$$

$$\text{On obtient : } \begin{cases} u'(t) = 1 \\ v(t) = \sin t \end{cases}$$

$$N = \left[t \sin t \right]_0^{\frac{\pi}{2}} - \int_0^{\frac{\pi}{2}} \sin t \, dt$$

$$N = \left[t \sin t \right]_0^{\frac{\pi}{2}} + \int_0^{\frac{\pi}{2}} -\sin t \, dt$$

$$N = \left[t \sin t \right]_0^{\frac{\pi}{2}} + \left[\cos t \right]_0^{\frac{\pi}{2}}$$

$$N = \left(\frac{\pi}{2} \sin \frac{\pi}{2} - 0 \cdot \sin 0 \right) + \left(\cos \frac{\pi}{2} - \cos 0 \right)$$

Finalement

$$N = \frac{\pi}{2} - 1$$

$$O = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} e^x \cos x \, dx \quad \text{On effectuera deux intégrations par parties successives.}$$

$$\text{On pose } \begin{cases} u(x) = e^x \\ v'(x) = \cos x \end{cases} \quad \text{on obtient : } \begin{cases} u'(x) = e^x \\ v(x) = \sin x \end{cases}$$

$$O = [e^x \sin x]_{-\frac{\pi}{2}}^{\frac{\pi}{2}} - \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} e^x \sin x \, dx$$

$$\text{On pose } \begin{cases} u(x) = e^x \\ v'(x) = \sin x \end{cases} \quad \text{on obtient : } \begin{cases} u'(x) = e^x \\ v(x) = -\cos x \end{cases}$$

$$O = [e^x \sin x]_{-\frac{\pi}{2}}^{\frac{\pi}{2}} - \left([e^x (-\cos x)]_{-\frac{\pi}{2}}^{\frac{\pi}{2}} - \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} e^x (-\cos x) \, dx \right)$$

$$O = [e^x \sin x]_{-\frac{\pi}{2}}^{\frac{\pi}{2}} - [e^x (-\cos x)]_{-\frac{\pi}{2}}^{\frac{\pi}{2}} - \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} e^x \cos x \, dx$$

$$O = [e^x \sin x]_{-\frac{\pi}{2}}^{\frac{\pi}{2}} - [e^x (-\cos x)]_{-\frac{\pi}{2}}^{\frac{\pi}{2}} - O$$

$$2O = [e^x \sin x]_{-\frac{\pi}{2}}^{\frac{\pi}{2}} + [e^x \cos x]_{-\frac{\pi}{2}}^{\frac{\pi}{2}}$$

$$2O = [e^x (\sin x + \cos x)]_{-\frac{\pi}{2}}^{\frac{\pi}{2}}$$

$$2O = e^{\frac{\pi}{2}} \left(\sin \frac{\pi}{2} + \cos \frac{\pi}{2} \right) - e^{-\frac{\pi}{2}} \left(\sin \left(-\frac{\pi}{2} \right) + \cos \left(-\frac{\pi}{2} \right) \right)$$

$$2O = e^{\frac{\pi}{2}} (1+0) - e^{-\frac{\pi}{2}} (-1+0)$$

$$2O = e^{\frac{\pi}{2}} + e^{-\frac{\pi}{2}}$$

Finalement

$$O = \frac{e^{\frac{\pi}{2}} + e^{-\frac{\pi}{2}}}{2}$$

Rq : $O = \text{ch } \frac{\pi}{2}$ (voir formulaire \rightarrow cosinus hyperbolique)

$$P = \int_0^{\pi} e^{-x} \sin 4x \, dx \quad \text{On effectuera deux intégrations par parties successives.}$$

$$\text{On pose } \begin{cases} u(x) = e^{-x} \\ v'(x) = \sin 4x \end{cases} \quad \text{on obtient : } \begin{cases} u'(x) = -e^{-x} \\ v(x) = -\frac{1}{4} \cos 4x \end{cases}$$

$$P = \left[e^{-x} \left(-\frac{1}{4} \right) \cos 4x \right]_0^p - \int_0^p -e^{-x} \left(-\frac{1}{4} \right) \cos 4x dx$$

On pose $\begin{cases} u(x) = -e^{-x} \\ v'(x) = -\frac{1}{4} \cos 4x \end{cases}$ on obtient : $\begin{cases} u'(x) = e^{-x} \\ v(x) = -\frac{1}{16} \sin 4x \end{cases}$

$$P = \left[e^{-x} \left(-\frac{1}{4} \right) \cos 4x \right]_0^p - \left(\left[-e^{-x} \left(-\frac{1}{16} \right) \sin 4x \right]_0^p - \int_0^p e^{-x} \left(-\frac{1}{16} \right) \sin 4x dx \right)$$

$$P = \left[e^{-x} \left(-\frac{1}{4} \right) \cos 4x \right]_0^p - \left[\frac{1}{16} e^{-x} \sin 4x \right]_0^p - \frac{1}{16} \int_0^p e^{-x} \sin 4x dx$$

$$P = \left[e^{-x} \left(-\frac{1}{4} \right) \cos 4x \right]_0^p - \left[\frac{1}{16} e^{-x} \sin 4x \right]_0^p - \frac{1}{16} P$$

$$P + \frac{1}{16} P = \left[-e^{-x} \left(\frac{1}{4} \cos 4x + \frac{1}{16} \sin 4x \right) \right]_0^p$$

$$\frac{17}{16} P = -e^{-p} \left(\frac{1}{4} \cos 4p + \frac{1}{16} \sin 4p \right) - (-e^0) \left(\frac{1}{4} \cos 0 + \frac{1}{16} \sin 0 \right)$$

$$\frac{17}{16} P = -e^{-p} \left(\frac{1}{4} + 0 \right) + \left(\frac{1}{4} + 0 \right)$$

$$\frac{17}{16} P = \frac{1 - e^{-p}}{4}$$

$$P = \frac{16(1 - e^{-p})}{4 \cdot 17}$$

Finalement

$$P = \frac{4(1 - e^{-p})}{17}$$

TD2 – Intégration par changement de variable – Proposition de correction**Exercice 1**

$$I = \int_{-1}^1 \frac{dx}{\sqrt{3x+5}}$$

On posera $u = 3x + 5 \dots$ On pose $u = 3x+5$ soit $1 \cdot du = 3 \cdot dx$ donc $dx = \frac{du}{3}$

$$\begin{aligned} I &= \int_{3(-1)+5}^{3 \cdot 1+5} \frac{du}{3\sqrt{u}} \\ &= \int_2^8 \frac{2du}{3 \cdot 2\sqrt{u}} \\ &= \frac{2}{3} \int_2^8 \frac{du}{2\sqrt{u}} \\ &= \frac{2}{3} \left[\sqrt{u} \right]_2^8 \\ &= \frac{2}{3} (\sqrt{8} - \sqrt{2}) \\ &= \frac{2}{3} (2\sqrt{2} - \sqrt{2}) \end{aligned}$$

Finalement

$$I = \frac{2\sqrt{2}}{3}$$

$$J = \int_0^1 (x+1)e^{x^2+2x} dx$$

On posera $u = x^2 + 2x \dots$ On pose $u = x^2+2x$ soit $du = (2x+2) dx$ donc $du = 2(x+1) dx$

$$\begin{aligned} J &= \int_{0^2+2 \cdot 0}^{1^2+2 \cdot 1} e^u \frac{du}{2} \\ &= \frac{1}{2} \int_0^3 e^u du \end{aligned}$$

$$= \frac{1}{2} [e^x]_0^3$$

$$= \frac{1}{2} (e^3 - e^0)$$

Finalement

$$J = \frac{e^3 - 1}{2}$$

$$K = \int_{-1}^0 \sqrt{t+2} \, dt$$

On posera $u = t + 2$

On pose $u = t + 2$ soit $t = u - 2$ et $du = dt$

$$\begin{aligned} K &= \int_{-1+2}^{0+2} (u-2)\sqrt{u} \, du \\ &= \int_1^2 (u-2)u^{\frac{1}{2}} \, du \\ &= \int_1^2 u^{\frac{3}{2}} - 2u^{\frac{1}{2}} \, du \\ &= \left[\frac{1}{\frac{3}{2}+1} u^{\frac{3}{2}+1} \right]_1^2 - 2 \left[\frac{1}{\frac{1}{2}+1} u^{\frac{1}{2}+1} \right]_1^2 \\ &= \left[\frac{2}{5} u^{\frac{5}{2}} \right]_1^2 - 2 \left[\frac{2}{3} u^{\frac{3}{2}} \right]_1^2 \\ &= \frac{2}{5} \cdot 2^{\frac{5}{2}} - \frac{2}{5} \cdot 1^{\frac{5}{2}} - 2 \left(\frac{2}{3} \cdot 2^{\frac{3}{2}} - \frac{2}{3} \cdot 1^{\frac{3}{2}} \right) \\ &= \frac{2}{5} \cdot \sqrt{2^5} - \frac{2}{5} - 2 \left(\frac{2}{3} \cdot \sqrt{2^3} - \frac{2}{3} \right) \\ &= \frac{2}{5} \cdot 4\sqrt{2} - \frac{2}{5} - 2 \left(\frac{2}{3} \cdot 2\sqrt{2} - \frac{2}{3} \right) \\ &= \frac{8\sqrt{2}}{5} - \frac{2}{5} - \frac{8\sqrt{2}}{3} + \frac{4}{3} \end{aligned}$$

Finalement

$$K = \frac{-16\sqrt{2}+14}{15}$$

$$L = \int_{-1}^1 (1-x) \sqrt{1-x^2} \, dx$$

On posera $x = \cos t$

On pose $x = \cos t$ soit $dx = -\sin t \, dt$ et $t = \text{Arcos } x$

$$\begin{aligned} L &= \int_{\text{Arcos}(-1)}^{\text{Arcos}(1)} (1-\cos t) \sqrt{1-\cos^2 t} (-\sin t) \, dt \\ &= \int_{-\pi}^0 (1-\cos t) \sqrt{\sin^2 t} (-\sin t) \, dt \end{aligned}$$

$$\begin{aligned}
&= \int_{-p}^0 (1 - \cos t)(-\sin t)(-\sin t) dt \text{ car } \sin t < 0 \text{ sur } [-p; p] \text{ donc } \sqrt{\sin^2 t} = -\sin t \\
&= \int_{-p}^0 (1 - \cos t)(\sin^2 t) dt \\
&= \int_{-p}^0 (1 - \cos t)(1 - \cos^2 t) dt \quad \text{car } \sin^2 t + \cos^2 t = 1 \\
&= \int_{-p}^0 (1 - \cos^2 t - \cos t + \cos^3 t) dt \\
&= \int_{-p}^0 \left(1 - \frac{1 + \cos 2t}{2}\right) - \cos t + \cos^3 t dt \\
&= \int_{-p}^0 \left(1 - \frac{1 + \cos 2t}{2}\right) - \cos t + \left(\frac{1}{4} \cos 3t + \frac{3}{4} \cos t\right) dt \text{ car } \cos^3 t = \frac{1}{4} \cos 3t + \frac{3}{4} \cos t \\
&\quad \text{(voir chapitre complexes – linéarisation)} \\
&= \int_{-p}^0 \left(\frac{1}{2} - \frac{5}{8} \cos t - \frac{1}{2} \cos 2t + \frac{1}{4} \cos 3t\right) dt \\
&= \left[\frac{t}{2} - \frac{5}{8} \sin t - \frac{1}{4} \sin 2t + \frac{1}{12} \sin 3t \right]_{-p}^0 \\
&= (0 - 0 - 0 + 0) - \left(\frac{-p}{2} - 0 - 0 + 0 \right)
\end{aligned}$$

Finalement

$$J = \frac{p}{2}$$

$$M = \int_0^1 \sqrt{\frac{1-x}{1+x}} dx$$

On posera $x = \cos t$ On pose $x = \cos t$ soit $dx = -\sin t dt$ et $t = \arccos x$

$$\begin{aligned}
M &= \int_{\arccos(1)}^{\arccos(0)} \sqrt{\frac{1 - \cos t}{1 + \cos t}} (-\sin t) dt \\
&= \int_{\frac{p}{2}}^0 \sqrt{\frac{(1 - \cos t)(1 - \cos t)}{(1 + \cos t)(1 - \cos t)}} (-\sin t) dt \\
&= \int_{\frac{p}{2}}^0 \sqrt{\frac{(1 - \cos t)^2}{1 - \cos^2 t}} (-\sin t) dt \\
&= \int_{\frac{p}{2}}^0 \sqrt{\frac{(1 - \cos t)^2}{\sin^2 t}} (-\sin t) dt \\
&= \int_{\frac{p}{2}}^0 \frac{\sqrt{(1 - \cos t)^2}}{-\sin t} (-\sin t) dt
\end{aligned}$$

car sur $[-\frac{p}{2}; 0]$ $\sin t < 0$ donc $\sqrt{\sin^2 t} = -\sin t$

$$= \int_{-\frac{p}{2}}^0 \frac{1 - \cos t}{-\sin t} (-\sin t) dt$$

car sur $[-\frac{p}{2}; 0]$ $1 - \cos t > 0$ donc $\sqrt{1 - \cos^2 t} = \sin t$

$$= \int_{-\frac{p}{2}}^0 (1 - \cos t) dt$$

$$= [t - \sin t]_{-\frac{p}{2}}^0$$

$$= (0 - 0) - (-\frac{p}{2} - (-1))$$

$$= -(-\frac{p}{2} + 1)$$

Finalement

$$M = \frac{p}{2} - 1$$

$$N = \int_3^4 \frac{t+1}{(t-2)^2} dt$$

On posera $x = t - 2$

On pose $x = t - 2$ soit $t = x + 2$ et $dx = dt$

$$N = \int_{3-2}^{4-2} \frac{x+2+1}{x^2} dx$$

$$= \int_1^2 \frac{x+3}{x^2} dx$$

$$= \int_1^2 \left(\frac{x}{x^2} + \frac{3}{x^2} \right) dx$$

$$= \int_1^2 \left(\frac{1}{x} + \frac{3}{x^2} \right) dx$$

$$= \left[\ln x - \frac{3}{x} \right]_1^2$$

$$= \left(\ln 2 - \frac{3}{2} \right) - \left(\ln 1 - 3 \right)$$

$$= \ln 2 - \frac{3}{2} + 3$$

Finalement

$$N = \ln 2 + \frac{3}{2}$$

$$O = \int_0^1 \frac{dx}{(x^2+1)^2}$$

On posera $x = \tan t$

On pose $x = \tan t$ soit $t = \text{Arctan } x$ et $dx = 1 + \tan^2 t = \frac{1}{\cos^2 t} dt$

$$O = \int_{\text{Arctan}(0)}^{\text{Arctan}(1)} \frac{(1 + \tan^2 t) dt}{(\tan^2 t + 1)^2}$$

$$= \int_0^{\frac{p}{4}} \frac{dt}{1 + \tan^2 t}$$

$$= \int_0^{\frac{p}{4}} \frac{dt}{\frac{1}{\cos^2 t}}$$

$$= \int_0^{\frac{p}{4}} \cos^2 t dt$$

$$= \int_0^{\frac{p}{4}} \frac{1 + \cos 2t}{2} dt$$

$$= \frac{1}{2} \left[t + \frac{1}{2} \sin 2t \right]_0^{\frac{p}{4}}$$

$$= \frac{1}{2} \left[\left(\frac{p}{4} + \frac{1}{2} \sin 2 \frac{p}{4} \right) - \left(0 + \frac{1}{2} \sin 0 \right) \right]$$

$$= \frac{1}{2} \left(\frac{p}{4} + \frac{1}{2} \cdot 1 \right)$$

Finalement

$$O = \frac{p+2}{8}$$

Exercice 2

$$1. \quad I = \int_0^{\frac{p}{w}} t \sin(wt) dt$$

$$\text{On pose } \begin{cases} u = t \\ v' = \sin(vt) \end{cases}$$

On obtient

$$\begin{cases} u' = 1 \\ v = -\frac{1}{v} \cos(vt) \end{cases}$$

$$I = \left[-\frac{t}{v} \cos(vt) \right]_0^{\frac{p}{v}} - \int_0^{\frac{p}{v}} -\frac{1}{v} \cos(vt) dt$$

$$= \left[-\frac{t}{v} \cos(vt) \right]_0^{\frac{p}{v}} + \frac{1}{v} \int_0^{\frac{p}{v}} \cos(vt) dt$$

$$= \left[-\frac{t}{v} \cos(vt) \right]_0^{\frac{p}{v}} + \frac{1}{v} \left[\frac{1}{v} \sin(vt) \right]_0^{\frac{p}{v}}$$

$$= \left[-\frac{t}{v} \cos(vt) \right]_0^{\frac{p}{v}} + \frac{1}{v^2} [\sin(vt)]_0^{\frac{p}{v}}$$

$$= -\frac{1}{v} \left(\frac{p}{v} \cos\left(v \frac{p}{v}\right) - 0 \cos 0 \right) + \frac{1}{v^2} \left(\sin\left(v \frac{p}{v}\right) - \sin 0 \right)$$

$$= -\frac{p}{v^2} \cos p + \frac{1}{v^2} \sin p$$

Finalement

$$I = \frac{p}{v^2}$$

$$2. \quad J = \int_0^{\frac{p}{v}} t (\cos(vt) + i \sin(vt)) dt$$

$$J = \int_0^{\frac{p}{v}} t \cos(vt) dt + i \underbrace{\int_0^{\frac{p}{v}} t \sin(vt) dt}_I$$

On a bien

$$I = \operatorname{Im}(J)$$

$$3. \quad J = \int_0^{\frac{p}{v}} t e^{i v t} dt$$

On pose $\begin{cases} u = t \\ v' = e^{i v t} \sin(vt) \end{cases}$

On obtient

$$\begin{cases} u' = 1 \\ v = \frac{1}{i v} e^{i v t} \end{cases}$$

$$J = \left[t \frac{1}{i v} e^{i v t} \right]_0^{\frac{p}{v}} - \int_0^{\frac{p}{v}} \frac{1}{i v} e^{i v t} dt$$

$$J = \left[t \frac{1}{i v} e^{i v t} \right]_0^{\frac{p}{v}} - \frac{1}{i v} \int_0^{\frac{p}{v}} e^{i v t} dt$$

$$J = \left[t \frac{1}{i v} e^{i v t} \right]_0^{\frac{p}{v}} - \frac{1}{i v} \left[\frac{1}{i v} e^{i v t} \right]_0^{\frac{p}{v}}$$

$$J = \left[t \frac{1}{i v} e^{i v t} \right]_0^{\frac{p}{v}} - \left(\frac{1}{i v} \right)^2 [e^{i v t}]_0^{\frac{p}{v}}$$

$$J = \frac{1}{i v} \left[t e^{i v t} \right]_0^{\frac{p}{v}} + \frac{1}{v^2} [e^{i v t}]_0^{\frac{p}{v}}$$

$$J = \frac{1}{i v} \left(\frac{p}{v} e^{i v \frac{p}{v}} - 0 \cdot e^0 \right) + \frac{1}{v^2} (e^{i v \frac{p}{v}} - e^0)$$

$$J = \frac{1}{i v} \left(\frac{p}{v} e^{i p} \right) + \frac{1}{v^2} (e^{i p} - 1)$$

$$J = \frac{p}{i v^2} e^{i p} + \frac{1}{v^2} (e^{i p} - 1) \quad \text{On utilise ensuite } e^{i p} = \cos p + i \sin p = -1 + i \cdot 0 = -1$$

$$J = \frac{p}{i v^2} (-1) + \frac{1}{v^2} (-1 - 1)$$

$$J = \frac{p}{i v^2} (-1) - \frac{2}{v^2}$$

$$J = \frac{p i}{i^2 v^2} (-1) - \frac{2}{v^2}$$

$$J = \frac{p i}{(-1) v^2} (-1) - \frac{2}{v^2}$$

$$J = -\frac{2}{v^2} + i \cdot \frac{p}{v^2}$$

On retrouve bien

$$I = \operatorname{Im}(J) = \frac{p}{v^2}$$

$$I = \frac{1}{v^2}$$